







| Question                          | Answer  | Marks    |
|-----------------------------------|---|----------|
| 1                                 | <b>Defining the problem</b>   |          |
|                                   | <i>m</i> is the independent variable and $\theta$ is the dependent variable <b>or</b> vary <i>m</i> and measure $\theta$<br><b>or</b><br>$\theta$ is the independent variable and <i>m</i> is the dependent variable <b>or</b> vary $\theta$ and measure <i>m</i> | <b>1</b> |
|                                   | keep position of load <u>constant</u> or <i>L</i> <u>constant</u>   | <b>1</b> |
|                                   | <b>Methods of data collection</b>   |          |
|                                   | labelled diagram of workable experiment including:<br>• load shown touching at P<br>• load labelled and at least one other label  | <b>1</b> |
|                                   | use a protractor to measure $\theta$  | <b>1</b> |
|                                   | if <i>m</i> is the independent variable: (slowly) change the angle until the block (just) topples<br><b>or</b><br>if $\theta$ is the independent variable: (slowly) change mass until block (just) topples  | <b>1</b> |
| use a balance to measure <i>m</i> | <b>1</b>  |          |

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| 1        | <b>Method of analysis</b>   |       |
|          | plot a graph of $\cos \theta$ against $1/m$ ( <b>or</b> reverse axes $1/m$ against $\cos \theta$ )<br>( <b>not</b> $1/\cos \theta$ against $m$ or $m$ against $1/\cos \theta$ )   | 1     |
|          | relationship valid if a straight line<br>( <b>not</b> ‘through the origin’ unless the choice of axes indicates the intercept is zero)   | 1     |
|          | $\alpha = \frac{2L \times \text{gradient}}{V \times w} \quad \text{or} \quad \alpha = \frac{\text{gradient}}{V \times y\text{-intercept}}$ <p>for reverse axes:</p> $\alpha = \frac{2L}{V \times w \times \text{gradient}} \quad \text{or} \quad \alpha = -\frac{1}{V \times y\text{-intercept}}$ | 1     |

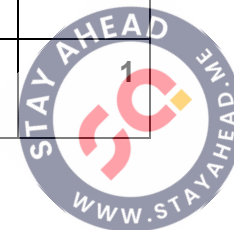


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| 1        | <b>Additional detail including safety considerations</b>  | <b>Max. 6</b> |
|          | D1 use cushion/foam/sandbox <u>in case block/load falls</u>   |               |
|          | D2 measure $L$ with a rule  |               |
|          | D3 correctly positioned protractor to measure $\theta$ , e.g. protractor with its centre over the nail and its straight edge parallel to an edge of the block   |               |
|          | D4 method to fix $m$ to strip   |               |
|          | D5 method to determine volume of block, e.g. $V = w \times h \times l$  |               |
|          | D6 measure $w$ , $h$ and $l$ with calipers/micrometer/rule  |               |
|          | D7 (if $m$ is the independent variable:) repeat experiment for $\theta$ <u>and</u> determine the average $\theta$<br><b>or</b><br>(if $\theta$ is the independent variable:) repeat experiment for $m$ <u>and</u> determine the average $m$   |               |
|          | D8 equation must be in the form of $y = mx + c$ with $\cos \theta$ on one side and $m$ on the other side<br>e.g. for a graph of $\cos \theta$ against $1/m$<br>$\cos \theta = \frac{\alpha V w}{2Lm} + \frac{w}{2L}$<br>or for a graph of $1/m$ against $\cos \theta$<br>$\frac{1}{m} = \frac{2L \cos \theta}{\alpha V w} - \frac{1}{\alpha V}$ |               |
|          | D9 method to determine centre of load or centre of block e.g. measure diameter/width and halve or diagonals across the block  |               |
|          | D10 method to ensure that block or strip is horizontal, e.g. check with a spirit level that table/block is horizontal or use a rigid strip  |               |



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|-----------------|---|---------|-------------|---------------|---------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|---------------|---------------|--|
| 2(a)            | gradient = $4\pi^2 M$   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 2(b)            | <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th><math>T / s</math></th> <th><math>T^2 / s^2</math></th> </tr> </thead> <tbody> <tr> <td>1.12 or 1.120</td> <td>1.25 or 1.254</td> </tr> <tr> <td>0.950 or 0.9500</td> <td>0.903 or 0.9025</td> </tr> <tr> <td>0.815 or 0.8150</td> <td>0.664 or 0.6642</td> </tr> <tr> <td>0.655 or 0.6550</td> <td>0.429 or 0.4290</td> </tr> <tr> <td>0.570 or 0.5700</td> <td>0.325 or 0.3249</td> </tr> <tr> <td>0.47 or 0.470</td> <td>0.22 or 0.221</td> </tr> </tbody> </table> | $T / s$ | $T^2 / s^2$ | 1.12 or 1.120 | 1.25 or 1.254 | 0.950 or 0.9500 | 0.903 or 0.9025 | 0.815 or 0.8150 | 0.664 or 0.6642 | 0.655 or 0.6550 | 0.429 or 0.4290 | 0.570 or 0.5700 | 0.325 or 0.3249 | 0.47 or 0.470 | 0.22 or 0.221 |  |
| $T / s$         | $T^2 / s^2$   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 1.12 or 1.120   | 1.25 or 1.254   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 0.950 or 0.9500 | 0.903 or 0.9025   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 0.815 or 0.8150 | 0.664 or 0.6642   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 0.655 or 0.6550 | 0.429 or 0.4290   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 0.570 or 0.5700 | 0.325 or 0.3249   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 0.47 or 0.470   | 0.22 or 0.221   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
|                 | Values of $T$ as above.   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
|                 | Values of $T^2$ as above.   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
|                 | Uncertainties in $T$ increase from $\pm 0.01$ to $\pm 0.02$ .   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
|                 | Uncertainties in $T^2$ about $\pm 0.02$ .   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 2(c)(i)         | Six points plotted correctly.<br>Must be accurate to the nearest half a small square. Diameter of points must be less than half a small square.   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
|                 | Error bars in $T^2$ plotted correctly.<br>All error bars to be plotted. Length of bar must be accurate to less than half a small square and symmetrical.  | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
| 2(c)(ii)        | Line of best fit drawn.<br>If points are plotted correctly then lower end of line should pass between (0.048, 0.5) and (0.052, 0.5) <b>and</b> upper end of line should pass between (0.098, 1.0) and (0.104, 1.0).   | 1       |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |
|                 | Worst acceptable line drawn (steepest or shallowest possible line that passes through all the error bars).<br>All error bars must be plotted.   |         |             |               |               |                 |                 |                 |                 |                 |                 |                 |                 |               |               |  |



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| 2(c)(iii) | Gradient determined with clear substitution of points from the line of best fit into $\Delta y / \Delta x$ .<br>Distance between points must be at least half the length of the drawn line. | <b>1</b> |
|           | uncertainty = gradient of line of best fit – gradient of worst acceptable line<br><b>or</b><br>uncertainty = $\frac{1}{2}$ (steepest worst line gradient – shallowest worst line gradient)  | <b>1</b> |
| 2(d)(i)   | $M$ determined from gradient <b>and</b> given to 2 or 3 significant figures <b>and</b> with correct unit.<br>$M = \frac{\text{gradient}}{4\pi^2} = \frac{\text{(c)(iii)}}{39.478}$          | <b>1</b> |
| 2(d)(ii)  | % uncertainty in $M$ = % uncertainty in gradient  | <b>1</b> |





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| 2(e)     | <p><math>k</math> calculated.<br/>Correct substitution of numbers required.</p> $k = \left( \frac{4\pi^2 M}{T^2} \right) = \frac{4\pi^2 (\mathbf{d})(\mathbf{i})}{2.5^2} \text{ or } 6.3165 \times (\mathbf{d})(\mathbf{i})$ <p><b>or</b></p> $k = \left( \frac{\text{gradient}}{T^2} \right) = \frac{(\mathbf{c})(\mathbf{iii})}{2.5^2} \text{ or } \frac{(\mathbf{c})(\mathbf{iii})}{6.25}$   | <b>1</b> |
|          | <p>Absolute uncertainty in <math>k</math>.<br/>Correct substitution of numbers required.</p> <p>Using <math>M</math>:</p> $\text{uncertainty in } k = \left( \frac{\Delta M}{M} + 2 \times \frac{\Delta T}{T} \right) \times k$ $\text{uncertainty in } k = \left( \frac{(\mathbf{d})(\mathbf{ii})}{100} + 0.008 \right) \times k$ $\max k = \frac{4\pi^2 \times \max M}{\min T^2} \text{ or } \min k = \frac{4\pi^2 \times \min M}{\max T^2}$ <p>Using gradient:</p> $\text{uncertainty in } k = \left( \frac{\Delta \text{gradient}}{\text{gradient}} + 0.008 \right) \times k$ $\max k = \frac{\max \text{gradient}}{\min T^2} \text{ or } \min k = \frac{\min \text{gradient}}{\max T^2}$ | <b>1</b> |

